Mathematical modelling of multiphase flows

The Fully Lagrangian Approach to turbulent flows: challenges, current status and future prospects

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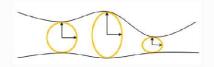
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Lagrangian Approach

Osiptsov method: The Fully

Osiptsov method



Cloud motion:

$$\frac{d\mathbf{x}^d}{dt} = \mathbf{V_d} \ , \ m_d \frac{d\mathbf{V}_d}{dt} = \mathbf{f}$$

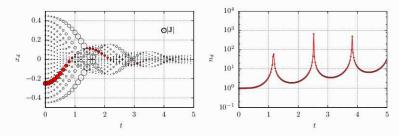
Mass conservation:

$$\frac{d}{dt} \int_{V_I(t)} n_d d\mathbf{x}^d = 0 \quad \Rightarrow \frac{d}{dt} \int_{V_0} n_d(\mathbf{x_0}, t) \det \left(J_{ij}(\mathbf{x_0}, t) \right) d\mathbf{x_0} = 0$$

Expression for the number density n_d :

$$n_d(\mathbf{x}_0, t) = \frac{n_d(\mathbf{x}_0, 0)}{||\mathbf{J}(\mathbf{x}_0, t)||} , J_{ij} = \frac{\partial x_i^d}{\partial x_{0,j}^d}$$

Osiptsov method



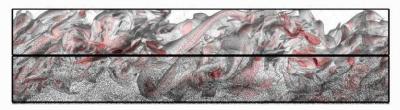
The initial value problem for the calculation of J:

$$\frac{\partial}{\partial t} \begin{bmatrix} J \\ \omega \end{bmatrix} = \begin{bmatrix} \omega \\ \frac{1}{\tau_d} \left(\frac{\partial U}{\partial x} J - \omega \right) \end{bmatrix} \;, \quad \text{ with } \begin{bmatrix} J \\ \omega \end{bmatrix}_{t=0} = \begin{bmatrix} 1 \\ \frac{\partial V}{\partial x} \end{bmatrix}$$

- FLA predicts n_d using a single cloud and identifies the infinitesimally small scales of the critical points (caustics)
- The ODE for J summarises the history of the droplet cloud trajectory
- ullet The critical points of 1/J do not degenerate the ODE for J

Challenges of implementing the FLA to turbulent flows

Challenges of implementing the FLA to turbulent flows



- Mass transport
- Momentum transport
- Turbulent diffusion modelling for inertia droplets
- Filtered number density, integrability of the point-wise FLA number density
- · Modelling of higher moments of number density

Current status

Mass transport

From the mass conservation equation in Eulerian form:

$$\frac{\partial \overline{n_d}}{\partial t} + \operatorname{div}(\overline{n_d \mathbf{V_d}}) = 0$$

we obtain

$$\frac{\partial \overline{n_d}}{\partial t} + \operatorname{div}(\overline{n_d} \overline{\mathbf{V_d}}) = -\operatorname{div} \mathbf{j_T}$$

by introducing the turbulent difussion flux j_T

$$\mathbf{j_T} = \overline{n_d' \mathbf{v_d'}} = \overline{n_d \mathbf{V_d}} - \overline{n_d} \overline{\mathbf{V_d}}$$

for a Lagrangian volume

$$\frac{D}{Dt} \int_{V_L} \overline{n_d}(\mathbf{x}, t) d\mathbf{x} = - \int_{V_L} \operatorname{div}(\mathbf{j_T}) d\mathbf{x}$$

Mass transport

Trasforming from the Lagrangian volume

$$\frac{D}{Dt} \int_{V_L} \overline{n_d}(\mathbf{x}, t) d\mathbf{x} = - \int_{V_L} \operatorname{div}(\mathbf{j_T}) d\mathbf{x}$$

To the initial Lagrangian volume at t=0

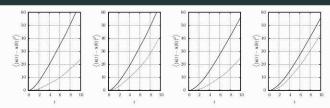
$$\frac{d}{dt} \int_{V_0} n_d(\mathbf{x}_0,t) \left| \det \left(\overline{J_{ij}}(\mathbf{x}_0,t) \right) \right| d\mathbf{x}_0 = - \int_{V_0} \operatorname{div}(\mathbf{j}_\mathsf{T}) \left| \det \left(\overline{J_{ij}}(\mathbf{x}_0,t) \right) \right| d\mathbf{x}_0 \;.$$

we obtain the FLA expression for the mass conservation in a filtered turbulent flow field

$$\frac{d}{dt}\left[n_d(\mathbf{x}_0,t)\left|det\left(\overline{J_{ij}}\right)\right|\right] = -\left|det\left(\overline{J_{ij}}\right)\right|\operatorname{div}(\mathbf{j}_{\mathsf{T}})$$

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Turbulent diffusion modelling for inertia droplets



The analogy to Brownian motion (Xia 2013) supports the use of the Fick's law for the modelling of turbulent diffussion

$$\mathbf{j}_T = -D_T \nabla n_s$$
, $D_T = \langle v_i^2 \rangle T_I = \sqrt{\langle v_i^2 \rangle} \mathcal{L}$

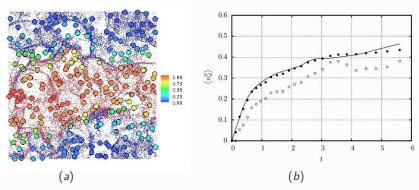
$$\frac{d\mathcal{V}^2}{dt} = \frac{1}{3} \frac{d}{dt} \overline{v_i' v_i'} = \frac{1}{3} \overline{2v_i' \frac{dv_i'}{dt}} = \frac{2}{\tau_d} \left(\frac{1}{3} \overline{v_i' u_i'} - \frac{1}{3} \overline{v_i' v_i'} \right) = \frac{2}{\tau_d} \left(\mathcal{U}^2 e^{-B\frac{\tau_d}{\tau_t}} - \mathcal{V}^2 \right)$$

Simplistic closure (Chen 1994), actually D_T changes with L

$$\frac{1}{3}\overline{v_i'u_i'} = \mathcal{U}^2 e^{-B\tau_d/\tau_t}.$$

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Turbulent diffusion modelling for inertia droplets



Mass conservation:

$$n_d(\mathbf{x}_0, t) = \frac{n_d(\mathbf{x}_0, 0)}{||\mathbf{J}(\mathbf{x}_0, t)||} + \frac{\int_{\tau=0}^{\tau=t} ||\mathbf{J}(\mathbf{x}_0, \tau)|| \nabla \cdot (D_T \nabla n_d(\mathbf{x}_0, \tau)) d\tau}{||\mathbf{J}(\mathbf{x}_0, t)||}$$

Momentum transport

The momentum trasport equation (Marble 1970):

$$\frac{\partial \overline{n_d} \overline{\mathbf{V_d}}}{\partial t} + \operatorname{div} \left(\overline{n_d} \overline{\mathbf{V_d}} \cdot \overline{\mathbf{V_d^T}} \right) = \frac{1}{\tau_d} \overline{\left(\mathbf{U} - \mathbf{V} \right) n_d} \; .$$

Assumming that $d\mathbf{j_T}/dt=0$ and $\frac{1}{ au_d}\overline{\left(\mathbf{U}-\mathbf{V}\right)n_d}=\frac{1}{ au_d}\overline{n_d}\left(\overline{\mathbf{U}}-\overline{\mathbf{V}}\right)$

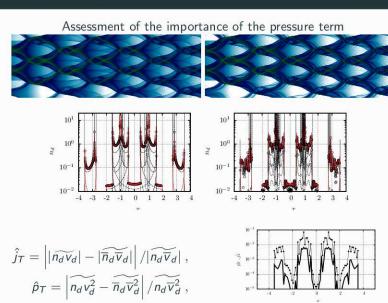
$$\frac{\partial \overline{n_d} \overline{\mathbf{V_d}}}{\partial t} + \operatorname{div} \left(\overline{n_d} \overline{\mathbf{V_d}} \cdot \overline{\mathbf{V_d^T}} \right) = \frac{1}{\tau_d} \overline{n_d} \left(\overline{\mathbf{U}} - \overline{\mathbf{V}} \right) + \operatorname{div} \mathbf{p} \; .$$

where \mathbf{p} is the pressure term:

$$p_{ij} = \overline{n_d V_{d,i} V_{d,j}} - \overline{n_d} \overline{V_{d,i}} \ \overline{V_{d,j}}$$

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Momentum transport



Momentum transport

Dropping the pressure term

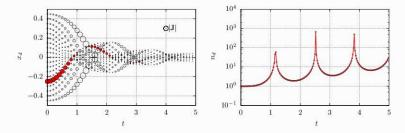
$$\frac{\partial \overline{n_d} \overline{\mathbf{V_d}}}{\partial t} + \operatorname{div} \left(\overline{n_d} \overline{\mathbf{V_d}} \cdot \overline{\mathbf{V_d^T}} \right) = \frac{1}{\tau_d} \overline{n_d} \left(\overline{\mathbf{U}} - \overline{\mathbf{V}} \right) \ .$$

and applying the Reynolds transport theorem

$$\frac{D}{Dt} \int_{V_L} \overline{n}_d(\mathbf{x}, t) \overline{\mathbf{V}}_{\mathbf{d}} dV = \int_{V_L} \overline{n}_d \frac{1}{\tau_d} \left(\overline{\mathbf{U}} - \overline{\mathbf{V}}_{\mathbf{d}} \right) dV$$

we obtain the simplified momentum transport equation having assummed that $d\mathbf{j_T}/dt=0$, $\frac{1}{\tau_d}(\mathbf{U}-\mathbf{V})\,n_d=\frac{1}{\tau_d}\overline{n_d}\,(\overline{\mathbf{U}}-\overline{\mathbf{V}})$ and $\mathbf{p}=\mathbf{0}$

$$\frac{d\mathbf{V_d}}{dt} = \frac{1}{\tau_d} \left(\mathbf{\overline{U}} - \mathbf{\overline{V_d}} \right) .$$

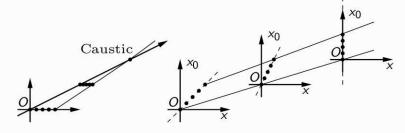


Inertia particles accumulate in Caustic regions where J=0, for which the number density is considered integrable (Osiptsov 1984)

$$n_d = \frac{n_d^0}{J}$$

Attempting to expand the number density did not result to the calculation of the finite number density within ${\it V}$

$$\int_{V} n_{d} d\mathbf{x} = \int_{V} \frac{1}{\mathbf{J}} d\mathbf{x} = \int_{V} \left(\frac{1}{J} \Big|_{0} + \frac{\partial}{\partial x} \frac{1}{J} \Big|_{0} x ... \right) dx$$

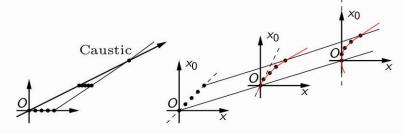


The FLA can be seen as a first order (linear) approximation of the structure for the dispersed continuum

$$n_d = \frac{\partial x_0}{\partial x}$$

where for
$$\delta = x_0 - x_0^C$$
 and $\epsilon = x - x^C$

$$\epsilon = J\delta$$
 with $J = \left. \frac{\partial \epsilon}{\partial \delta} \right|_0$



Introducing a second order description for the dispersed continuum

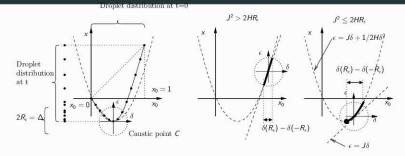
$$\epsilon(\delta) = J\delta + \frac{1}{2}H\delta^2.$$

the filtered number density defined in a finite volume R_{ϵ}

$$\hat{n}_d = \frac{1}{2R_{\epsilon}} \int_{-R_{\epsilon}}^{R_{\epsilon}} n_d d\epsilon = \left| \frac{\delta(\epsilon = R_{\epsilon}) - \delta(\epsilon = -R_{\epsilon})}{2R_{\epsilon}} \right| ,$$

where H is the Hessian of the transformation

$$H = \frac{\partial^2 \epsilon}{\partial \delta^2} = \frac{\partial^2 x}{\partial x_0^2}$$

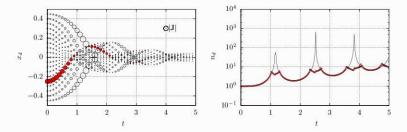


From the expression of the current coordinate ϵ

$$\delta(\epsilon) = \frac{-J + \sqrt{J^2 + 2H\epsilon}}{H}$$

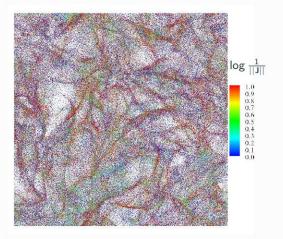
we obtain
$$\hat{n}_d = \left| \left(\delta(\epsilon = R_{\epsilon}) - \delta(\epsilon = -R_{\epsilon}) \right) / (2R_{\epsilon}) \right|$$

$$\hat{n}_d = \begin{cases} \frac{2}{\sqrt{J^2 + 2HR_\epsilon} + \sqrt{J^2 - 2HR_\epsilon}} & \text{if } J^2 - 2HR_\epsilon > 0 \\ \\ \frac{\sqrt{J^2 + 2HR_\epsilon}}{2R_\epsilon H} & \text{if } J^2 - 2HR_\epsilon < 0 \ . \end{cases}$$

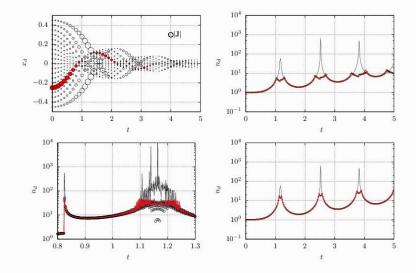


To calculate the filtered number density we need to solve an ODE of the Hessian too.

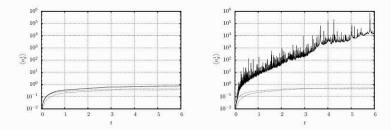
$$\frac{\partial}{\partial t} \begin{bmatrix} J \\ \omega \\ H \\ \psi \end{bmatrix} = \begin{bmatrix} \omega \\ \frac{1}{\tau_d} \left(\frac{\partial U}{\partial x} J - \omega \right) \\ \psi \\ \frac{1}{\tau_d} \left(\frac{\partial^2 U}{\partial x^2} J^2 + \frac{\partial U}{\partial x} H - \psi \right) \end{bmatrix}, \quad \text{with} \quad \begin{bmatrix} J \\ \omega \\ H \\ \psi \end{bmatrix}_{t=0} = \begin{bmatrix} 1 \\ \frac{\partial V}{\partial x} \\ 0 \\ \frac{\partial^2 V}{\partial x^2} \end{bmatrix}$$



For 3D cases we currently assume that the caustic formations are 1D thus a primary direction can be defined for $\delta = x_0 - x_0^C$ and $\epsilon = x - x^C$



Modelling of higher moments of number density



Higher moments of the number density (Reeks 2014) in turbulent flow fields can be predicted using the second order FLA

$$\langle n_d^a \rangle = \left\langle \frac{n_d}{|\mathbf{J}|^{a-1}} \right\rangle$$

Closure

Future prespectives

- Use of the finite volume number density \hat{n}_d for the modelling of higher moments for n_d in turbulent flows
- Extension of the second order FLA for the capturing of structues with more than one dimension (enlogated or collapsed caustic formations)
- Introduction of more advanced models for the turbulent diffussion of inertia droplets and particles
- Account for the pressure term in the conservation of momentum and/or the rate of the turbulent mass flux
- Calculation of the Jacobian and the Hessian matricies for non-Stokesian drag forces

Clonclusion

- FLA provides a robust and efficient method to calculating the fine structure of the dispersed continuum
- The Singularities of the FLA number density are important to identify caustic formations and do not affect the solution
- The second order FLA predicts the value of n_d on any finite volume with size R_ϵ providing a link to the filtering width of the LES framework, and converges to the standard FLA for $R_\epsilon \to 0$